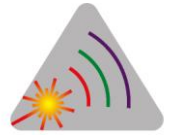


## Datasheet LaserMicrometer LM28

### General:

- |                                   |   |
|-----------------------------------|---|
| - Operating voltage:              | 10V .... 26V                              |
| - Current consumption @ 12V:      | < 130 mA                                  |
| - Output OBJEKT_DETECT:           | open collector, < 80 mA, active LOW       |
| - Interface:                      | RS232, TXD, RXD                           |
| - Laser:                          | 655nm laser class 1M                      |
| - Housing:                        | Aluminum, black anodized, potential free  |
| - Housing dimensions (L x W x H): | 136 mm x 86 mm x 22 mm (see Appendix `C´) |
| - Weight:                         | 270g                                      |
| - Mounting:                       | 5 holes, D = 3.2 mm                       |
| - Temperature range in operation: | 0°C ..... 50°C                            |
| - Temperature range in stock:     | -25° ..... 75°C                           |



Measurement data (Optics LYDIA)

- Measuring range: 0.2 mm ..... 28 mm
- Resolution: 0.4375 µm
- Repeat accuracy Edge mode: +/- 10 µm
- Repeat accuracy Dia mode: +/- 20 µm
- Non-linearity Edge mode: +/- 20 µm
- Non-linearity Dia mode: +/- 35 µm
- Reaction time: < 1 ms
- Measuring rate: max. 1000 measurements / s
- Measuring modes: Edge mode, Dia -mode (see Appendix `B`)

Serial Interface:

- Connector: 10-pin. header, RM 2.54, for IDC socket
- Signals: RXD, TXD, GND
- Baud rate: 4800, 9600, 19200, 38400, 57600, 115200  
selectable via coding switch
- more Settings: Data bits: 8, parity: without, stop bits: 1,  
Flow control: without

Encoding switch:	Switch position:	Baud rate:
	0	4800
	1	9600
	2	19200
	3	38400
	4	57600
	5	115200
	6	F invalid

After changing the switch position, the device must be restarted to recognize the set baud rate.

**Pin assignment:**

Pin	Signal	Remarks
1	TXD-SENSOR	Output RS232
2	RXD-SENSOR	Input RS232
3	OBJECT-DETECT	Output, open collector, active low
4	TRIGGER-IN	Input 0 / 5V, not activated
5	n.c.	Not connected
6	FRAME	Without function, output, open collector
7	+5V	Output , 5V, for service only
8	n.c.	Not connected
9	+UB	Operating voltage. +10V ... 26V DC max. 200mA
10	GND	0V (GND)

**!!! Note !!!**

The filter glasses of the sensor are **not allowed to be touched** . Smallest impurities, as well as fingerprints affect the function. If necessary, clean the glasses with alcohol and a soft, lint-free cloth without residue.

## Appendix `A` Command – List LaserMicrometer LM28

### DATA COMMAND

Hex: <0x1X>, where X specifies amount of requested consecutive data's.  
 Sensor response: 2^x x DATA, multiple of 3bytes packet, min. 3 bytes.  
 3 BYTE FORMAT: <HIGH BYTE> >LOW BYTE> >INFO BYTE>  
 INFO BYTE FORMAT (8 bits): /OBJECT\_IN/0/#AVG\_VALID/0/0/M2/01/M0/  
 OBJECT\_IN bit: indicates presence of an Object  
 #AVG\_VALID: for higher stability sensor averages several readings, when  
 measuring mode is changed, old reading in the buffer would make  
 false result  
 M2/M1/M0/: measuring mode, see MODEs table on next page

#### Example 1:

PC request: <0x10> // request for 1 data  
 Sensor response: <0xA4> <0xB7> <82> // high byte, low byte, info byte  
 //Data = 0xA4B7=42167, this is diameter in pixels  
 //1 pixel = 0.4375 µm. Data (mm) = 42167\*0.4375=18.448  
 //Status byte: Object present, averaging is valid and mode=diameter

#### Example 2:

PC request: <0x14> // request for 16 consecutive data's  
 Sensor response: Sixteen 3 bytes packet (for conversion see MODE command below)

### DATA\_STREAM\_START

Hex: <0x21>, continuous DATA stream start, Sensor response: data stream of 3 bytes packets,  
 see DATA command

### DATA\_STREAM\_STOP

Hex: <0x20>, continuous DATA stream stop, Sensor response: no response

### MODE command

Hex: <0x3X>, where X specifies the measurement mode.  
 Sensor response (1 byte): <0x3X> //echo back

This parameter is not stored in the sensor after power OFF. It needs to be set after power ON event.

X	0000b	0001b	0010b
Mode	Edge 1	Edge 2	Dia

Table 2: Mode Table

See also Appendix `B` for more information on the various measurement modes.

**FIRMWARE command**

Hex: <0xF0> reads firmware version, Sensor response: two bytes

**LASER ON/OFF command**

Hex: <0x91> for Laser ON, <0x90> for Laser OFF, Sensor response: command echo

**UNLOCK command**

Hex: <0xFE1F9E0>, this command unlocks service commands reserved for skilled user only.  
Sensor response (1 byte): <E0>, signal, average, EEPROM access

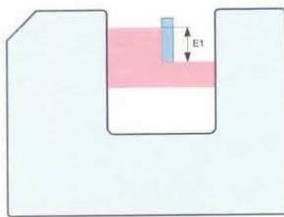
**READ\_RAW\_DATA command (unlock required)**

Hex: <0xD0>, this command reads light intensity profile of CMOS image sensor.  
Sensor response: 2137 bytes (2048 bytes image data + other information)

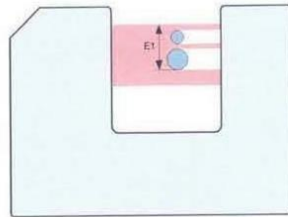
**READ\_THRESHOLD command (unlock required)**

Hex: <0xD1>, this command reads threshold data.  
Sensor response: 2137 bytes

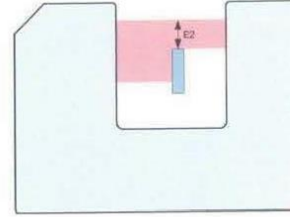
Appendix `B` Mess - Modi LaserMicrometer LM28



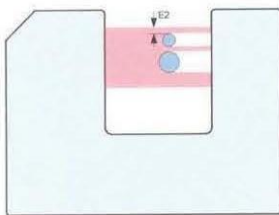
EDGE1 - MODE  
LEADING EDGE



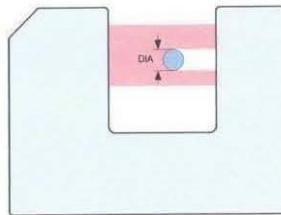
EDGE1 - MODE  
MULTIPLE OBJECTS



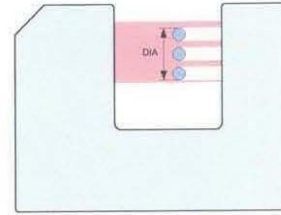
EDGE2 - MODE  
TRAILING EDGE



EDGE2 - MODE  
MULTIPLE OBJECTS



DIA - MODE



DIA - MODE  
MULTIPLE OBJECTS

Appendix `C` Mounting / Dimensions LaserMicrometer LM28

